Study on Wind Turbine and ItsAerodynamic Performance

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ABSTRACT

The study on wind turbines and their aerodynamic performance is what this paper seeks to convey. The sharp rise in the world's energy needs has drawn a lot of focus on the production of energy from renewable sources. Energy must be captured from all accessible resources, including those found in metropolitan areas, in order to satisfy renewable energy requirements. This essay is an analysis of wind turbines. The two types of wind turbines that were discussed in this paper are vertical axis wind turbines and horizontal axis wind turbines. The use of vertical axis wind turbines (VAWTs) as an urban energy source is considered to be a possibility. The majority of wind turbine research focuses on condition monitoring and performance optimization of VAWTs with constant air velocity, without taking into consideration transient impacts. The VAWT's life cycle could be shortened by the wind's unpredictable behaviour, which could alter the flow field surrounding it. This work aims to investigate and analyse the performance of a wind turbine under accelerating and decelerating air input velocity using computational fluid dynamics techniques. The Blade Element Momentum (BEM) theory and the modified stall model were used to construct a 10,000 Watt HAWT blade, and the blade aerodynamics were also simulated to look into the flow structures and aerodynamic properties.

Keywords: Vertical axis wind turbine, Horizontal-axis wind turbine, Reynold number

INTRODUCTION

Wind turbines work on a straightforward theory. Two or three blades that resemble propellers rotate around a rotor thanks to the wind's energy. The primary shaft, which spins a generator to produce electricity, is attached to the rotor. The technique of using the wind to produce mechanical or electrical energy is referred to as wind power or wind energy. The kinetic energy of the wind is converted into mechanical power by wind turbines. This mechanical power can be used for specific tasks (such as grinding grain or pumping water) or a generator can convert this mechanical power into electricity.

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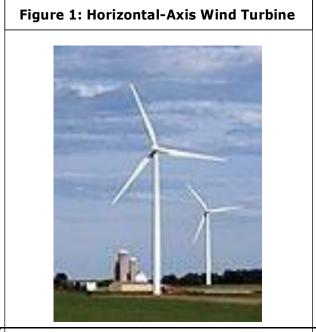
blade consists of the two dimensional(2D) airfoils, which result the lift and drag forces by virtue of pressure differences acrossthe 2D airfoil. Because of this, the Blade Element Momentum (BEM) theory is widely used to outline a procedure for the aerodynamic design of a HAWT blade. The design parameters, which include the rated wind speed, number of blades, design tip speed ratio, and design angle of attack, can be used to determine the best distributions of chord length and pitch angle in each segment (Manwell et al., 2009; Bai and Hsiao, 2010; and Hsiao and Bai, 2013). The torque output, which is also largely dependent on the rotor's ability to generate torque, determines how well wind turbines work. HAWT are more effective than VAWT, but they need high-quality wind energy. In urban areas where wind is in-consistent and highly fluctuating, VAWT is more beneficial due to its low starting torquecharacteristics as well as other advantages likebeing in-expensive to build and of simple design (Rohatgi and Barbezier, 1999; Manwellet al., 2009; and Park et al., 2012). Wind energy has become one of the fastest growingrenewable energy sources, because energygenerated by wind power is one of the cleanest energy resources available. As Horizontal-Axis Wind Turbine (HAWT) blades become lighterand more flexible, the system dynamics must be analyzed comprehensively in order to evaluate and understand the complex interaction of the elastic vibrations of the windturbines and the unsteady aerodynamic forcesacting on them. In line with the demand for lighter wind turbine blades, new advanced

fabrication methods and composite materials have been introduced, and this has resulted in reduced structural damping, which is a property that until very recently was impossible to model and enhance (Riziotis *et al.*, 2004).

TYPES OF WIND TURBINE

Horizontal-Axis Wind Turbine(HAWT)

Horizontal-Axis Wind Turbines (HAWT) have the main rotor shaft and electrical generator at the top of a tower, and must be pointed into the wind. Small turbines are pointed by a simple wind vane, while large turbines generally use a wind sensor coupled with a servo motor. Most have a gearbox, which turns the slow rotation of the blades into a quicker rotation that is more suitable to



vean electrical generator.

Vertical Axis Wind Turbines(VAWTs)

Vertical axis wind turbines are a type of turbine

turbines can rotate unidirectional even with bi- directional fluid flow. VAWT is mainly due to the advantages of this kind of machine over the horizontal axis type, such as their simple construction, the lack of necessity of over speed control, the acceptance of wind from any direction of the mechanical design limitations due to the control systems and the

Figure 2: Vertical Axis Wind Turbine

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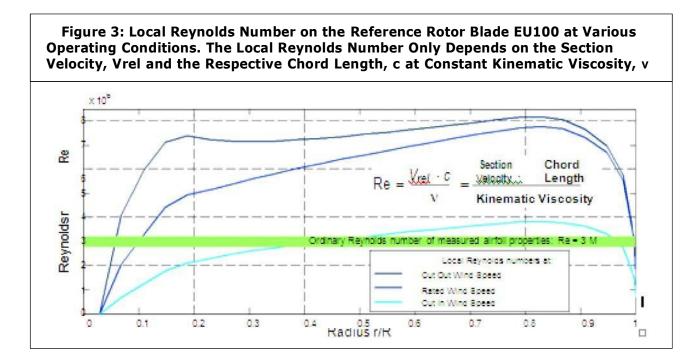
electric generators are set up statically on the ground. Generally, there have been two distinct types of vertical axis wind turbine that is the Darrieus and savonius types. For the Darrieus, there are three common blades that are Squirrel Cage Darrieus, H-Darrieus and Egg Beater Darrieus (David and Spera, 1998).

EFFECT OF REYNOLD NUMBER

For axial-flow (commonly referred to as horizontal-axis) turbines, small changes in angle of attack a of the local relative wind w.r.t. blade chord occur throughout blade rotation, and are due to mean shear in the boundary layer (which can also cause varying deformation) or turbulence. This means it's relatively easy to predict turbine performance with models that employ static foil section data, e.g., Blade Element Momentum (BEM) methods.

Reynolds Number Effects on WindTurbines

1. The maximum power coefficient CP.max is increased. This is caused by a lower drag



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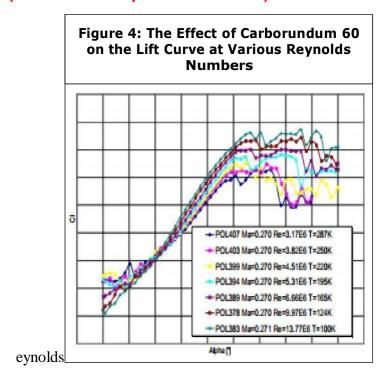
in the low drag bucket, which leads to less profile losses and thus a power coefficient which is closer to the theoretical maximum of CP = 0.59.

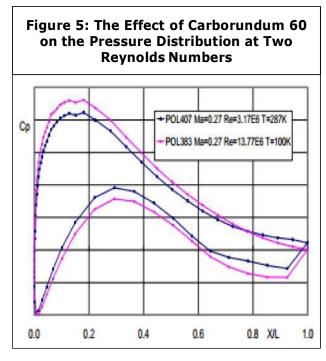
- 2. The power coefficient at low tip speed ratios is increased. The reason therefore is that more lift can be generated due to the higher maximum lift caused by the Reynolds number effect. Also less blade sections operate in stalled conditions which results in less drag. Hence profile losses are decreased at low tip speed ratios as well.
- 3. The shape of the power coefficient curve changes, its saddle becomes wider. This is a consequence of 1. And 2: less drag at the Best lift to drag ratio and higher stall angle of attack. This is Advantageous for operating conditions at non optimum tip speed Ratios, i.e., for operation at maximum speed below rated power.
- 4. The optimum blade set angle is increased. The reason therefore is that the best lift to drag ratio is shifted to smaller angles of attack and thus smaller lift coefficients. Hence the optimum performance is reached at smaller section in flow angles which is achieved by increasing the pitch.
- 5. The optimum tip speed ratio is increased. The reason therefore is that the optimum lift to drag ratio occurs at smaller angles of attack and hence at smaller lift coefficients. The decrease in lift coefficient is compensated by increasing the section velocity, which shifts the optimum tip speed ratio to higher values.
- 6. The thrust coefficient is increased at low tipspeed ratios, but can be partly decreased by increasing the blade set angle (AbbottIra *et al.*, 1945).

Reynolds Number Effect of Contaminated Profile

Figure 4 shows the Reynolds number effecton the lift coefficient. With increased

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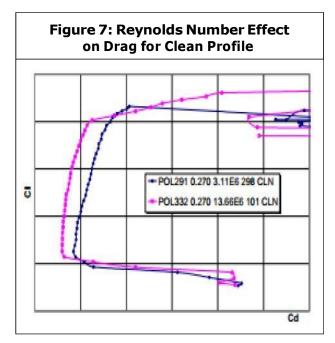


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numbers the boundary layer becomes thinner, but more powerful. The impact of carborundum thus decreases. The stall occurs at higher angle of attack, so climax increases.

Reynolds Number Effect of CleanProfile

For the clean thin profile the Reynolds number effect is typical, just like the description in the classical literature. As shown in Figures 6 and 7, with increased Reynolds number, Clmaxincreases, lift curve is more linear, its slope goes up slightly, Cdmindecreases and the laminar bucket becomes smaller. Figure 10a is a schematic of a straight-bladed-fixed-pitch VAWT which is the simplest, but typical form, of the Darrieus type VAWTs. Figure 10b illustrates typical flow velocities around a rotating VAWT blade at a given azimuthal angle θ , as well as the aerodynamic forces perceived by the blade. The azimuthal angle θ is set to be zero when the blade is at the top of the flight path and is increases in a counter-clockwise direction.



Reynolds Number Effect of FlowControl Devices

Figures 8 and 9 show the effect of a Gurney flap at two Reynolds numbers. It is clear that the selected Gurney flap suitable for the lowReynolds number is not optimal for the highReynolds number.

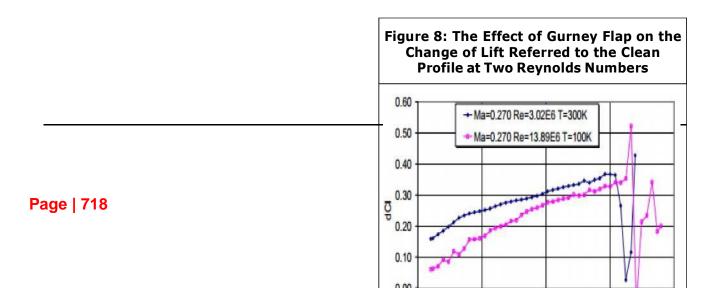


Figure 10: Basics of VAWT: a) Sketch

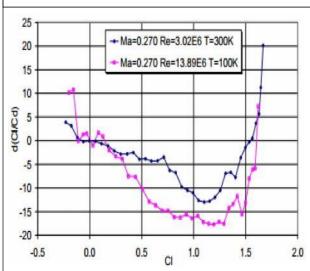
of a Fixed-Pitch Straight-Bladed VAWT;

Figure 6: Reynolds Number Effect on Lift for Clean Profile

-POL291 0.270 3.11E6 298 CLN
-POL332 0.270 13.66E6 101 CLN

Alpha

Figure 9: The Effect of Gurney Flap on the Change of Lift Drag Ratio Referred to the Clean Profile at Two Reynolds Numbers



AERODYNAMICS OF A VAWT

The movement of the blades in a VAWT entails a la operating condition. In order to understand the startic conditions experienced by the turbine blade when it rota

Figure 10a is a schematic of a straight- bladed-fixedform, of the Darrieus type VAWTs. Despite the simplicity, us acrouy name analysis is sun quite

b) Typical Flow Velocities in Darrieus **Motion** (a) (b) Flight path $\Omega_{\rm b}$ Vertical line

complex. One feature is that the relative velocities perceived by the blade always change as the blade moves at different azimuthal positions. Figure 10b illustrates typical flow velocities around a rotating VAWT blade at a given azimuthal angle θ , as well as the aerodynamic forces perceived by the blade.

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The azimuthal angle θ is set to be zero when the blade is at the top of the flight path and is increases in a counter-clockwise direction.

From the vectorial description of velocities, Figure 10b, we can obtain the following expression that establishes the relationship between the angle of attack D the Tip Speed Ratio (TSR) λ and the azimuthal angle θ of a blade in Darrieus motion (without velocity induction)

$$\tan \alpha_D = U \square \sin \theta / (\square R + U \square \cos \theta)$$

$$= \sin \theta / (\lambda + \cos \theta)$$
or
$$\alpha = \arctan(\sin \theta / \lambda + \cos \theta)$$

Another important parameter is the reduced frequency which governs the level of unsteadiness.

The reduced frequency k, defined as $k\omega = c/2Ueff$ where ω is the angular frequency of the unsteadiness, c is the blade chord and Ueff is the velocity of the blade, can be expressed in terms of TSR as:

$$k = (c/d)\lambda/\Box(\lambda^2 + 2\lambda \cos \theta + 1)$$

TIP SPEED RATIO OF WIND TURBINE

The Tip Speed Ratio (TSR) is an extremely important factor in wind turbine design. TSR refers to the ratio between the wind speed and the speed of the tips of the wind turbine blades.

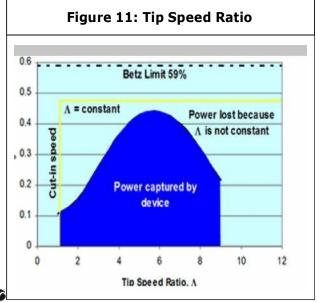
The Tip Speed Ratio (often known as the TSR) is of vital importance in the design of wind turbine generators. If the rotor of the wind turbine turns too slowly, most of the wind will pass undisturbed through the gap between the rotor blades. Alternatively if the rotor turns too quickly, the blurring blades will appear like a solid wall to the wind. Therefore, wind turbines are designed with optimal tip speed

ratios to extract as much power out of the windas possible.

Optimum Tip Speed Ratio

The optimum tip speed ratio depends on the number of blades in the wind turbine rotor. The fewer the number of blades, the faster the windturbine rotor needs to turn to extract maximumpower from the wind. A two-bladed rotor has an optimum tip speed ratio of around 6, a three-bladed rotor around 5, and a four-bladed rotor around 3. Different types of turbine have completely different optimal TSR values-for example a Darrieus wind turbine is a vertical axis (VAWT) design with aerofoil blades which generate aerodynamic lift and therefore the TSR can be high, but a Savonius wind turbine which is also a VAWT is a drag design and so the TSR will always be less than 1-i.e., it cannot spin faster than the

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ind hitting it.

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