

## COHERENCE OF LIBRARY CACHES

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**Abstract**— An effective approach for chip multiprocessors and multicores is directory-based cache coherence. The collection of acknowledgement messages and invocation messages for the directory protocol, however, need multicast, which can be expensive in terms of latency and network traffic. Furthermore, as the number of cores rises, so does the directory's size. We offer Library Cache Coherence (LCC), which eliminates the need for invalidation acknowledgements or broadcasting or multicasting invalidations. A library is a collection of timestamps that are used to delay writing to shared cache lines until all shared copies have expired and to automatically invalidate shared cache lines. The number of cores has no bearing on the size of the library. LCC produces fewer network messages since it does away with the intricate invalidation procedure of directory-based cache coherence protocols. When a write to a cache block is being delayed, LCC also permits reads on the block to occur without compromising sequential consistency. Consequently, even with a straightforward timestamp selection algorithm, LCC has 1.85X less average memory latency than a MESI directory-based protocol on our set of benchmarks; additionally, our experimental results on LCC with an ideal timestamp scheme (though not implementable) show the potential

### I. INTRODUCTION

With the demise of Dennard scaling, the increase in processor clock frequencies from 1980-2003 has slowed down significantly [1]. To improve performance, architects are exploring many parallel architectures including manycore architectures in academia (e.g., Raw [2], TRIPS [3]) and industry (e.g., Tiler [4], Intel TeraFLOPS [5]). In a manycore or multi-core architecture, cores with relatively low complexity are connected to memory and each other via high-bandwidth on-chip interconnect.

How will these multicores be programmed? Amongst many different types of parallel programming models, message passing and shared memory are the most dominant ones. Some multicores, for example, the Tiler Tile-Gx 100 provide a shared memory abstraction to the programmer, while other architectures like Intel

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TeraFLOPS rely on message passing. Message passing is a very efficient programming model for certain types of applications, such as scientific computation. However, many programs and operating systems are based on the shared memory abstraction, so it is indispensable for general-purpose multicores to support the shared memory abstraction.

On-chip cache memory cannot be *directly* implemented as a single large cache primarily because the energy consumption of caches grows quadratically with cache size, and because the number of read and write ports do not scale with the number of cores. To maintain performance, we need distributed caches that behave like a logically shared cache.

#### A. Directory-Based Cache Coherence (DirCC) Architecture

When we consider a two-level on-chip cache hierarchy for a tiled multicore architecture, there are many choices in implementing a logically shared cache. One of the most common approaches in modern multicore processors is to implement a *private* L1 cache and a *shared* L2 cache slice for each core (e.g., Tiler's 64-core processor [4], Cavium Octeon 32-core processor). A shared L2 cache architecture

unifies the per-core L2 cache slices into one large logically shared cache, and a memory address has a unique location where it can be cached on-chip, which is termed the *home* cache for the address. Therefore, data can be replicated in L1 but not in L2. On an L1 miss, the *home* L2 cache, where the data block may be located, needs to be looked up; the home can be a local L2 cache if the address is mapped to the requesting core's cache (*core hit*), or a remote L2 cache if the core is not the home for the address (*core miss*). While these remote accesses may lead to a higher average L2 hit latency, the on-chip cache is better utilized by not replicating any data in L2, reducing the number of expensive off-chip accesses when compared to a private L2 design.

The common shared memory abstraction model requires data coherence between cores. In this example of the shared L2 cache architecture, private L1 caches need

to be kept coherent. When the number of cores is large ( $> 32$ ), snoopy caches are no longer viable [6], and we are left with directory-based cache coherence [7]. There are difficulties in scaling directories to hundreds of cores, since the directory sizes grow with the number of cores. A fullmap directory is a directory that keeps track of all the sharers of each cache block [8]. If, say, we have 256 cores on the chip, we will require a 256-bit vector for each shareable cache block, unless compression techniques, e.g., [9], [10], are applied, which may degrade performance.

Moreover, directory protocols that maintain sequentially consistent operation may require up to four network messages, that include broadcast (multicast) to all (a subset of) cores, and return acknowledgements. Broadcast/multicast can be expensive in terms of latency and network traffic and therefore many techniques have been developed to alleviate this expense (e.g., [11], [12]).

### B. Our contribution: Library Cache Coherence Protocol (LCC)

We propose *Library Cache Coherence* (LCC), a novel cache coherence protocol which 1) does not require broadcast/multicast of invalidations (and therefore, no collection of invalidation acknowledgements), 2) is scalable to any number of cores, and 3) guarantees sequential consistency.

There are several points worth of note before we describe the LCC protocol:

- We assume a global timer that is available to all cores and caches. (This timer does not have to increment with the processor clock, and can be significantly slower.)
- Each memory address has a unique home L2 location.
- Each line in the L1/L2 cache has an additional timestamp. This timestamp is interpreted in two different ways. If the data block is *not* in its home L2 location, the timestamp indicates the time until when the line is valid (i.e., can be read), and if it is at its home L2, the timestamp holds the *maximum* value of timestamps among all the copies of the data block.
- A line can only be written at its home location, i.e., writes requested by a processor have to be sent to the home L2 cache.

We will describe the protocol informally here and more formally in Section III. A high-level example of LCC with a shared L2 cache is also illustrated in Figure 1. While a data block can only be written in its home L2 location, when a processor makes a request for a word in the data block, read-only copies of data blocks with timestamps can be stored in L1 caches. The timestamp assigned to the data block is assigned by the home L2 cache when it sends the block to the requesting core (cf. Figure 1a,1b). The requested *word* from the block is loaded into a register, and a copy of the block is stored in the local L1 cache provided that its timestamp has not expired. The home L2 cache keeps the information about the timestamps assigned to each data block that is stored in it, for those blocks that have been shared. Crucially, for any given data block, the home cache needs to just keep information about the *maximum* value of the timestamp assigned to any copy of the data block. Any write request to the data block in the home cache will not occur until the timestamp has expired. In other words, we delay writes to a block until all the read copies of the data block have expired in their respective locations to maintain sequential semantics (cf. Figure 1c,1d).

C. Comparing the Library and the Directory Protocol

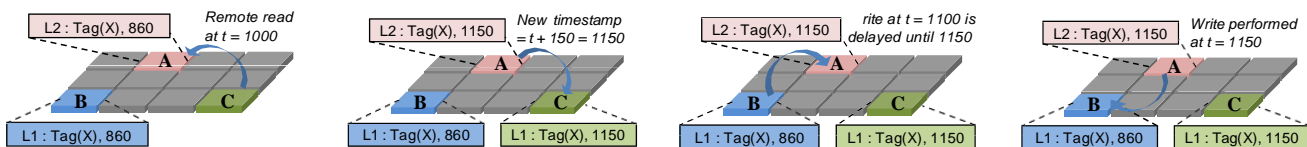
The library protocol does not require broad-cast/multicast of invalidation messages, and therefore it need not wait for invalidation acknowledgements to arrive, when writing to a shared cache line. However, as writes are only done at the L2 cache of the home core, they do not exploit spatio-temporal locality and may be delayed if the cache line being written has an unexpired copy elsewhere.

This implies that the choice of the timestamps is crucial to performance and we show how it affects the performance of LCC in Section IV-A.

For the directory-based protocol, directories are stored at L2 caches combined with cache blocks, and lines in L1 caches have state information on whether the line is shared or exclusive. On the other hand, the library protocol requires per-cache-line timestamps for both the L1 and L2 caches. In terms of scalability, the area overhead of directory-based protocols becomes greater as the number of cores grows, as the shared information grows linearly with the number of cores in a full-map directory scheme, whereas the library protocol incurs only a constant overhead independent of the number of cores by storing timestamps of fixed size in the L1 and L2 caches.

II. RELATED WORK

Reducing coherence overhead in distributed shared memory (DSM) has been widely explored over decades. Dynamic Self-Invalidation (DSI) [13] eliminates invalidation messages by having a processor self-invalidate its local copy of a cache block before a conflicting



(a) Suppose core B has a copy of address X in its L1 and its timestamp is 860. Core C wants to read X, but misses in its L1 cache, resulting in a remote read to the L2 cache at core A. The remote read arrives at supposedly,  $t = 1000$ .  $T_{delta}$ , 150, is added to the current clock, 1000, and data is sent back to core C (L1 cache) with this new timestamp of 1150. The timestamp at core A's L2 cache is also updated. When core B wants to write on X, it needs to perform a remote write to the home core A, and suppose it arrives at  $t = 1100$ . Since the current time has not past the timestamp (1150) yet, it should wait until  $t$  becomes greater than 1150.

(b) Once the timestamp has expired (i.e.,  $t > 1150$ ), the write can be performed and the acknowledgement is sent back.

Fig. 1. An example of LCC for the private L1 and shared L2 configuration : assume core A to be the home core for memory address X, and we add a constant  $T_{delta}$  of 150 to the system time to decide a new timestamp. Each box in the figure consists of *Tag* and *Timestamp* of the cache line for address X. Note that the entry in the home L2 cache always keeps the maximum value of timestamps given out by the home core, and other cores can hold the block only in their L1 caches.

memory request by another processor, and the directory needs to identify the blocks to be self-invalidated. DSI, however, still requires invalidation acknowledgements to maintain sequential consistency. Last-Touch Predictor (LTP) [14] predicts the "last touch" to a memory block by one processor before the block is accessed and subsequently invalidated by another using trace-based correlation. This, however, comes at a high cost; to learn a last-touch, all the invalidation messages for a processor must be exposed to the corresponding LTP, and the DSM controller needs to be integrated in the processor. Moreover, both DSI [13] and LTP [14] are built on top of a directory-based protocol since blocks that are not self-invalidated still need

to be explicitly invalidated in their [17]). The scheme in [17] is not sequentially consistent, and only supports a weaker notion of consistency, namely release consistency. In order to be sequentially consistent, we need to maintain a library of timestamps at the home cache, which also assigns timestamps for data requested. Our timestamps have two different meanings, and unlike in the scheme of [17], it is quite possible for a cache block to have expired by the time it arrives at the requesting core because of interconnect delays; we can, however, still use the word that was requested by the processor.

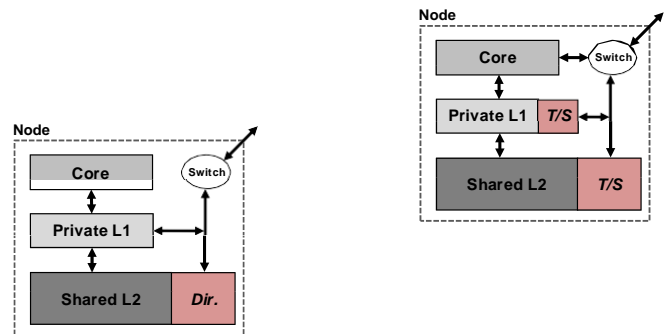
### III. LIBRARY CACHE COHERENCE

#### A. Baseline Architecture

conventional manner. This necessitates directories and sharer information; LCC eliminates the need for sharer information and therefore, is more scalable.

Timestamp-based approaches for self-invalidation were also proposed, but in the context of software cache coherence. Min and Baer [15] proposed a timestamp-based software-assisted cache coherence scheme which detects and invalidates the possibly incoherent cache

#### network



(a) Directory-based

(b) Library

#### Network

entry, essentially reassigning the entire burden of maintaining cache coherence to the compiler/software. Timestamp-based Selective Invalidation Scheme (TB-SIS) [16] explicitly invalidates stale cache copies using a special invalidation instruction if the corresponding variable is modified in the current epoch. Again, the compiler must insert this instruction at the proper place at compilation time. Unlike these schemes, library cache coherence is a full hardware coherence scheme and does not require additional compiler or software support.

Nandy and Narayan [17] proposed a hardware-based, auto-invalidate cache coherence protocol. They assume a fixed life-time  $t_c$  for each cache line that begins with the load of the data in the *requesting* cache (cf. Figure 3b Fig. 2. Baseline architectures for DirCC and LCC (T/S = timestamp))

Figure 2 shows the baseline architecture for directory-based CC (DirCC) and LCC. Although LCC can be implemented on either the private L2 or the shared L2 organization, we choose the shared L2 architecture (with private L1) as a baseline, and use the same architecture for both DirCC and LCC for a fair comparison.

As shown in Figure 2a, directories and L2 caches are integrated for DirCC, so the sharer information is contained together with each cache line. LCC does not require directories, but instead requires per-cache-line timestamps for both the L1 and L2 caches (Figure 2b). Under the shared L2 architecture, each memory address has a unique home location. In this paper, we

use a static data placement scheme, *striping*, at page granularity, which allows the computation of the home core from the memory address using simple logic.

Since data cannot be replicated in shared L2 caches, each L2 slice can maintain only the *home* data, and the data fetched from remote L2 caches can only be cached in L1. For the library protocol, it is important to note that the timestamp of L1 and that of L2 have different meanings. A timestamp in the L1 cache line indicates the time until when the block can be read. A timestamp in the L2 cache, on the other hand, keeps the *maximum* value of timestamps that have been assigned by the home L2 cache, until when the L2 cache must prevent writing on the block. As all read copies at L1 caches will be discarded when their timestamps expire, the home L2 cache can write to the block when the system time becomes larger than the maximum timestamp value stored at the L2 cache.

### B. Baseline Protocol

Below is the full description of library cache coherence protocol:

- *Read* operations

- 1) At the requesting core : The requesting core first looks up its local L1 cache, and proceeds to the L2 cache of the home location if it misses in its L1. The request to the L2 cache will be a local access if the request gets a *core hit*, and a remote access if it gets a *core miss*. Note that an L1 cache block will be invalid when its timestamp expires, so it won't get a cache hit on an expired cache line.
- 2) At the home L2 cache : If the data does not exist in the L2 cache, it will first be brought to the cache from the DRAM. Once the cache block is ready, it is returned to the requester core along with a timestamp. Timestamp choosing logic is used to decide whether to use the old timestamp which was previously given to other L1 caches, or to use a new timestamp. The maximum timestamp among all timestamps issued to L1 caches is kept in the L2 cache.

- *Write* operations

- 1) At the requesting core : A write request is directly forwarded to its home L2. L1 caches do not have to be looked up for writes, since writes can be only done in home L2 locations and L1 caches only maintain read-only copies.
- 2) At the home L2 cache : If the data does not exist in the L2 cache, it will be first brought to the cache from the DRAM. Once the cache block is ready, the L2 cache checks if its timestamp has expired. If it has not expired yet, the write is delayed until the current system time reaches the timestamp value and the line has expired; this is a *write delay*. When a cache block is brought in from DRAM, it has a null timestamp (cf. Section III-E.)

### C. Request Scheduling at the L2 Cache (Home)

Multiple requests on the same cache line may arrive at an L2 cache at the same time. Scheduling of these requests is very important in order to provide functional correctness and to prevent starvation. The library protocol processes one request at a time, serializing both read and write requests on the cache block. Read requests and write requests are treated the same, and we assume a fair scheduling between requests from the local L1 cache and remote L1 caches. When a write request is being delayed due to an unexpired timestamp, however, the protocol holds the blocked write request until the timestamp expires and processes other read requests if available. This may cause a read request that arrived later to be processed before a blocked write request. However, this still maintains sequential consistency since the reordered execution sequence is yet another sequential interleaving of programs. We have assumed in-order cores that have a single outstanding write request to simplify the requirements for sequential consistency. However, this assumption is not strictly required for LCC as conventional techniques to support sequential consistency for multi-issue or out-of-order cores can be applied to LCC as well without significant modifications.



#### D. Choosing Timestamps

As shown in the protocol, timestamps affect whether memory reads in L1 caches result in hits or misses, and also affect the amount of write delays at L2 caches. If a timestamp is too small, a core gets more L1 read misses as its read copy is invalidated too soon. If it is too large, on the other hand, the write delays will compromise system performance. Thus, timestamp choosing logic plays a critical role in determining the performance of library cache coherence.

Here, we present the simplest timestamp strategy, namely a FIXED-DELTA scheme. FIXED-DELTA uses a constant value  $T_{delta}$  to decide timestamps. When a read request for block X is being processed at its home L2 cache:

- 1) if there is a write request on the same block X waiting to be served, the current timestamp of the L2 entry is returned without any change to prevent increasing write delay.
- 2) otherwise, a new timestamp for the read request is calculated as  $(current\ clock + T_{delta})$  at the home L2 cache, and is returned to the requesting core's L1 cache with the data block.

TABLE I  
SYSTEM CONFIGURATIONS

Parameter	Settings
Cores	64 in-order, single issue cores
L1 cache/ core associativity	8 KB, 2-way set associativity L2 cache/ core associativity
	128KB, 4-way set

We also implement and evaluate an IDEAL scheme; in IDEAL, home L2 caches are assumed to know when the

#### L1/L2 Replacement Policy LRU/LRU

next write request on each cache line *will* arrive, and/or when each cache line *will* be evicted by a capacity miss. Timestamps are set to the time when the earlier event will happen, so read requests get the maximum timestamp values that do not delay any writes or evictions. Although IDEAL is not implementable in real hardware, the performance of IDEAL tells us the performance potential for LCC, provided we have a smart timestamp choosing scheme that can predict close to optimal timestamp values. While relegating the development of such a scheme to future work, we sweep the value of  $T_{delta}$  for scheme FIXED-DELTA, and show how close the best FIXED-DELTA scheme can perform when compared to the IDEAL scheme (cf. Section IV).

#### E. Cache Replacement Policy

The library protocol can be implemented with any conventional cache replacement scheme with one modification to ensure the correctness of the protocol. While L1 cache evictions can be done anytime, an L2 cache entry with unexpired copies should not be evicted until all the copies expire. If the cache entry gets evicted, we lose track of the timestamp for the corresponding entry, and thus, we cannot fetch the correct timestamp value when the entry is restored from memory — this will break sequential consistency. This restriction may result in cache eviction delays if all the entries in multiple ways of the L2 cache happen to have unexpired copies.

## IV. EVALUATION

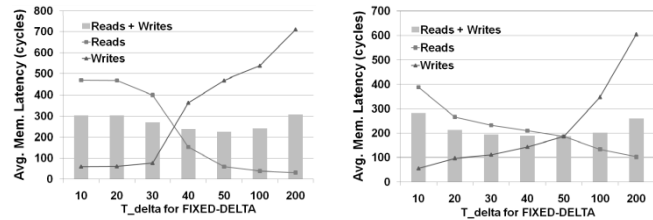
Using Pin [18] and Graphite [19], we first generate memory instruction traces for a set of SPLASH-2 benchmarks [20]: FFT, LU CONTIGUOUS, OCEAN, RADIX and WATER. Then, we feed these traces

to HORNET [21], a cycle-level multicore simulator, which models the interconnect behavior (e.g., congestion) in a cycle-accurate manner. The important system parameters used in the experiments are listed in Table I.

#### A. FIXED-DELTA with varying $T_{\delta}$

We first swept the value of  $T_{\delta}$  for the FIXED- DELTA scheme, and Figure 3 shows a tradeoff between

L1/L2 Access Latency	2 cycles/4 cycles	Cache Line Size	32 bytes
Electrical network	2D Mesh, XY routing, 64-bit flits		
Data Placement	STRIPE, 4 KB page size	Directory Coherence	MESI, Full-map distributed directory
DRAM Access Latency	50 cycles	One-way Off-chip La-	150 cyclestency
Simulated Cycles	5,000,000 cycles		



(a) FFT (b) LU CONTIGUOUS

Fig. 3. Average memory latency for varying  $T_{\delta}$ . Other benchmarks are not shown for lack of space, but have the same trends.

the read latency and write latency. As we increase  $T_{\delta}$ , the L1 cache hit rate for reads increases because the entry becomes valid for a longer period of time, resulting in lower average memory latency for reads. For writes, however, the average latency increases with a larger  $T_{\delta}$  due to the write delays. The combination of these two factors determine the optimal range of  $T_{\delta}$  which minimizes the overall memory latency; for our experiments,  $T_{\delta}$  between 50 and 100 showed the best performance depending on the benchmark, but without a big difference in performance within the range.

#### B. Performance Comparison with DirCC and LCC-IDEAL

Figure 4 shows the performance of the best FIXED- DELTA LCC and the IDEAL LCC, both normalized to the MESI directory protocol. For all the benchmarks we run except for OCEAN, LCC shows better performance than DirCC, and on average (geometric mean), the best LCC-Fixed outperforms DirCC by 1.85x. This performance gain mainly comes from the fact that 1) LCC does

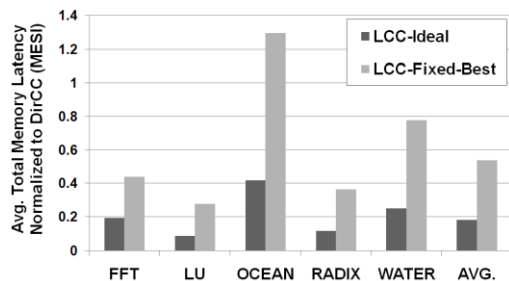


Fig. 4. Average overall memory latency for the LCC-Ideal and the best LCC-Fixed normalized to the MESI directory protocol.

not send out invalidation requests and wait for their acknowledgements, and 2) LCC can serve subsequent read requests while delaying a write on the same line maintaining sequential consistency. Moreover, the performance of the ideal LCC is much better (outperforms DirCC by 5.5x), showing the potential for further improvement of LCC. For example, since each cache line has a different access pattern, a timestamp choosing scheme that captures such patterns and assigns different  $T_{delta}$ 's for each line at runtime may provide better performance.

## V. CONCLUSIONS

We presented a library cache coherence protocol that can replace conventional directory-based cache coherence protocols in manycore architectures. LCC outperforms a directory-based MESI protocol as it avoids expensive invalidations before a write on a shared cache line. Also, it serves read requests first when a write is pending because it is not allowed to write on a cache line, which further increases the memory access performance while maintaining sequential consistency. LCC is also more scalable than directory-based coherence since library size does not grow with the number of cores. We believe that the performance of LCC can be improved further with more sophisticated schemes of choosing timestamps, which provides an interesting research problem to the community. Finally, while we have focused on sequential consistency in this paper, LCC can also improve performance for weaker memory consistency models.

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